AHSANULLAH UNIVERSITY OF SCIENCE AND TECHNOLOGY
DEPARTMENT OF MECHANICAL ENGINEERING

ME 3102: Mechanics of Machinery Sessional
Experiment No. 02

OBJECTIVE

- To become familiar with epicyclic gearing systems and gear selection.
- To be able to determine velocity ratios of epicyclic gear systems experimentally and analytically.
- To determine torque and power transmission.

Epicyclic gearing or planetary gearing is a gear system consisting of one or more outer gears, or planet gears, revolving about a central, or sun gear. Typically, the planet gears are mounted on

![Epicyclic Gearing Diagram](image)

a movable arm which itself may rotate relative to the sun gear. Epicyclic gearing systems also incorporate the use of an outer ring gear or annulus, which meshes with the planet gears. Epicyclic gears are typically classified as simple and compound epicyclic gears. Simple epicyclic gears have one sun, one ring, one carrier, and one planet set.

Experimental Setup:
1) Graduated disc  
2) Input shaft  
3) Output shaft  
4) Disc D  
5) Ring  
6) Sun gear  
7) Planet gears (3 Units)

Power reaches the epicyclic gear through the central sun gear, that is to say, the input shaft is joined to the central sun pinion and the output power is obtained at the output shaft which is joined to the ring gear.

The shafts of the unit are made of stainless steel and the discs are made of aluminium. All the pinions are made of aluminium and mounted on ball bearings. It will allow low inertia and a reduction of losses due to friction making the practical execution easy.

**Gear selection and determining velocity ratio:**

Sun and Annulus Gears fixed together (Direct drive)

To calculate velocity ratio for direct drive the clutch (disc D) must be coupled to the ring of the epicyclic gear unit through a pin. As it can be observed the planetary gearing rotates as a whole.

Sun Gear Fixed (Overdrive)

To calculate velocity ratio of overdrive a pin is introduced in the disc D groove, which will simulate the braking of the central sun gear with a band brake. With the carrier arm being the input shaft and the annulus gear the output shaft, experimentally determine the velocity ratio between the input and output shafts.

**Velocity ratio for different arrangement:**

<table>
<thead>
<tr>
<th>Gear arrangement</th>
<th>Direct drive</th>
<th>Overdrive</th>
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<tbody>
<tr>
<td>Velocity Ratio</td>
<td>Experimenta</td>
<td>Analytical</td>
</tr>
<tr>
<td>1</td>
<td>Analytical</td>
<td>Experimental</td>
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</table>
**Torque and power transmission**

The power generated by an internal combustion engine is measured by two magnitudes: the power and the motor torque. This ratio is frequently referred as RPM and it varies depending on the engine and its designs. When increasing the RPM of an engine, the torque reaches its maximum before the power reaches its maximum. Therefore, it can be stated that one of the transmission objectives is to allow keeping the engine working in a stable range between the torque peak and the power peak. With a transmission, the engine can be kept within this stability range by changing the turning ratio of the engine and wheels, increasing the speed of the engine until it has a greater power to maintain the speed.

Determination of torque and power transmission at overdrive:

1. Put mass at one end of the rope.
2. Let the mass fall free and count the rotation of the graduated disc at the input and output with a stopwatch.
3. Take readings for seven masses.
4. Calculate torque at the input and output using the formula, Torque input, $\tau_i = F*r$

    Ignoring friction losses, $\tau_o = \tau_i / \omega_i$

    So, Torque output, $\tau_o = \tau_i / \omega_i / \omega_o$

5. Calculate power transmitted, $P = \tau_i$

Radius of input graduated disc: Sun gear teeth, $Z_1 = 21$

Length of the Rope: Planet gear teeth, $Z_2 = 21$

Ring Gear teeth, $Z_3 = 63$

<table>
<thead>
<tr>
<th>No. Observation</th>
<th>Mass Kg</th>
<th>Input Velocity, $N_i$ RPM</th>
<th>Output Velocity, $N_o$ RPM</th>
<th>Velocity Ratio, $N_i / N_o$</th>
<th>Input Torque, $\tau_i$ Nm</th>
<th>Output Torque, $\tau_o$ Nm</th>
<th>Torque Ratio</th>
<th>Power Transmitted W</th>
</tr>
</thead>
</table>
Discussion:

- Briefly explain how the epicyclic gear system works and its use in practical life.
- Explain what you understand by direct drive and overdrive.
- Explain the torque and power curve obtained.
GEARS
A gear is a rotating machine part having cut teeth, which mesh with another toothed part to transmit torque. For meshing the module of the gears must be same. Module is defined as,

\[ m = \frac{D}{N} \]

Where \( D \) is the pitch circle diameter and \( N \) is the number of teeth.

Gears transmit power and provides mechanical advantage. [Mechanical advantage is a measure of the force amplification achieved by using a tool]

GEAR TYPES

Spur Gear

Bevel Gear

Helical Gear

Double Helical Gears or Herringbone Gears

Fig3: Different Gear types

MANUAL TRANSMISSION

Power from the engine goes to wheels via manual transmission, drive shaft, differential to wheel in a front (mounted) engine rear wheel drive, FR. Clutch connects the transmission to engine.

Fig4: Transmission of power in an automobile.

Fig5: ZF 6-speed manual transmission
SIMPLE GEAR BOX OPERATION

Fig 6: Simple gear box

Neutral Position

First gear

Fig 7: A six speed gearbox handle mark

DIFFERENTIAL

The differential is a device that splits the engine torque two ways, allowing each output to spin at a different speed.

Fig 8: Path taken by two wheels is different while turning

Fig 9: CAD view of an open type differential

Fig 10: Differential in Automobiles
LAMBORGHINI GALLARDO

550 hp @ 1000 rpm
0-60mph in 3.9s
Top speed 200mph
Rim Dia 19in

405kw @ 1000rpm
0-100kmh in 3.9s
Top speed 320kmh
Rim Dia 0.4826m

Now, per rev of rim the path traveled,
Distance = \pi D
Distance= 1.51m

Now while accelerating, the required rpm for
100kmh is,
V=28m/s
\omega= 18.54 rps
\omega=1112.58 rpm

At top speed,
V=90m/s
\omega= 3600 rpm

Engine provides,
P = \tau \omega
\tau = F \times d
For accelerating we need F
For speed we need \omega

QUESTIONS
2. Calculate the \omega for 21in rim dia.
3. What is a limited slip differential? How it differs from our open type one? Draw a neat sketch of a LSD.
4. Provide power transmission diagram for an automobile using automatic transmission.
5. Differentiate between automatic and manual transmission.
power transmission
mechanical advantages

Gears make when module are same.

Schematics:

At first gear power division
At top gear power division

\[ F_W \rightarrow \omega \rightarrow F_T \]

\[ F_T = M_a \cdot a_a \]

So, we need more \( a_a \) at sta starting, so more \( F_T \) is needed so more \( \omega \) is needed.

Manual manual transmission uses "clutch" and automatic transmission uses "Torque Converter".

Limited Slip Differential (LSD) used for limiting the slip of wheels while on ice or hole; i.e. when no traction on a wheel.

Gears on layshaft are pre-build on it. Gears on transmission shaft are freely rotating until meshed with collar. Collar is fixed with transmission shaft.
Gyroscope

A gyroscope is a device for measuring or maintaining orientation, based on the principle of preserving angular momentum.

Effect of the Gyroscopic Couple on an Aeroplane

The top and front view of an aeroplane are shown below. Let engine or propeller rotates in the clockwise direction when seen from the rear or tail end and the aeroplane takes a turn to the left.

Terms Used in a Naval Ship

The top and front views of a naval ship are shown in Fig 14.7. The fore end of the ship is called bow and the rear end is known as stern or aft. The left hand and right hand sides of the ship, when viewed from the stern are called port and star-board respectively. We shall now discuss the effect of gyroscopic couple on the naval ship in the following three cases: Steering, pitching, and rolling.
Figure: Naval ship terms; naval ship taking a Left turn.

Figure: Pitching of naval ship.

Data Table

<table>
<thead>
<tr>
<th>No of Obs.</th>
<th>Arm length (cm)</th>
<th>Weight (gm)</th>
<th>Torque (gm.cm)</th>
<th>Time of precession (s)</th>
<th>No of rev.</th>
<th>Precessional speed (rad/s)</th>
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Graph
Torque vs. precessional speed.

Questions
1. Why Rolling has no gyroscopic effect on naval ships?
2. How gyroscope can be helpful to maintain balance in aero plane and ships?
3. Discuss the gyroscopic effects while an Aero plane taking a right turn.
4. Discuss the gyroscopic effects while a naval ship taking a right turn.